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# Automatic Detection of Brain Tumour in MRI Images using Neural Network Classifier

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***Abstract:*** *The brain is among the largest and most complex organs that control all the human body's metabolic activities. Abnormalities or injuries in the brain cause grievous problems and are sometimes lethal. Moreover, the development and metastasis of the tumor can be monitored and treated appropriately by MRI accurately. MRI can also render information on the surrounding tissues, necrotic tissues, and the active cancer tissue significant in tumor diagnosis for early therapy and continuous monitoring. Therefore, accurate segmentation of brain images is a very complicated and untiring task. Glioblastoma is antithetic to other brain tumors because of its penetrating and fuzzy structure. To identify and locate the glioblastoma exactly, the image segmentation requires details of borders and edges in specific. This regards multimodal image segmentation, and it demands deep learning approaches since there is more than one modal to be dealt with for an accurate prediction. This study strategizes multimodal semantic image segmentation to detect and diagnose brain tumors. Deep learning Multimodal Convolution Neural Network (MMCNN) with U-NET has been utilized in the proposed methodology to achieve effective image segmentation.*

***Keywords:*** *U-NET, MMCNN, multimodal image segmentation.*

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## 1. Introduction

The MRI renders various types of contrast tissue images which allow for obtaining important morphological information [9]. This information collected facilitates the segmentation and diagnosis of tumorous abnormalities and their sub-regions. There is four standard MRI classification utilized for diagnosing glioma diagnoses as T1-weighted MRI (T1), T2- weighted MRI (T2), T1-weighted MRI with gadolinium contrast enhancement (T1-Gd), and Fluid Attenuated Inversion Recovery (FLAIR [2]. The MRI data acquisition differs from every device, and it takes nearly 150 slices of 2D images to constitute the 3D brain volume [10-15]. Moreover, the data is complicated and densely populated when these slices are combined based on the diagnosis requirement.T1 images obtained are used to differentiate the healthy tissues from the abnormal ones. T2 images are specifically used to identify the regions with edema that render bright signals on the images, and T1-Gd images show the tumor's borders that are differentiated from the bright signals due to the accumulation of gadolinium [1]. The bright accumulation occurs in the abnormal tissues' active cellular regions on the images, while necrotic tissues do not interact with the contrast dye [16-21]. This variation in the tumor's hypointense regions facilitates segmentation efficiency from examining the same tumor's active parts [22].

Automatic segmentation can be an ideal technique for efficient segmentation of MRI images over manual and semi-automatic brain tumor segmentation methods [23-27]. Despite the advantages, automatic segmentation is a challenging technique for gliomas diagnosis because the MRI data is in 3D format, which imbibes shapes, size, and location [3]. These variables are highly different in every patient, and the tumor boundaries are mostly unclear with lots of separations, making them challenging for edge-based segmentation [28-34]. The glioma MRI data are usually complicated due to ununiformed protocols followed during scanning [35-43]. These data impose biased intensities for every individual dataset utilized, making it challenging to combine entire modalities pileup more complexity for effectively segmenting the tumor sub-regions [4].

## 2. Literature Survey

Convolutional Neural Networks (CNN) or deep autoencoders are the deep learning methods developed to influence image segmentation and object detection, localization, and classifications. When the smaller kernels are convoluted over larger images, the convolution process sums up products between the input and kernel weights [44-47]. To obtain a 2D matrix, the smaller kernels with x and y directions are added and convoluted with the K channels of a tumor image. Training such kernels with CNN generates activation maps corresponding to certain objects' features. Based on the type of activation, CNN can be considered a segmentation mask of the object being analyzed as a unique feature [48-55]. This provides the essential requirement for segmentation embedded in the output activation matrices considered advantageous to segmentation that uses CNN.In CNN, at first, the earlier layers capture local features like the contour or a small part of the objects in the image, then later capture the global features in detail [5].

The traditional CNNs have been challenging to handle inputs of different sizes because the layers were fully interconnected [56-61]. This Fully Convolutional Networks **(**FCNs) have been designed to use all the convolutional layers together, even with varying input sizes in a workable manner. The image's height and width are represented by the final output layers that possess a more significant receptive field [62-67]. The number of channels would be constituted based on the number of classes. The images' exact location and context are found by classifying all the convolution layers' pixels [68].

Furthermore, the segmentation algorithms could also be dealt with as boundary detection techniques where the earlier layers can render refined details and the latter on the coarser boundaries[6]. Troupe learning incorporates the results of different related scientific models to a solitary spread. Group learning can enhance forecast exactness and cut down speculation blunders [69-74]. This takes into consideration the exact characterization and division of pictures [75]. Outfit learning division includes an option for one ideal student creation by producing a bunch of powerless base-students that group portions of the picture and consolidate their results [7].

DeepLab is a high-level division approach that helps control the sign obliteration, consequently chopping down the number of tests and the amount of information the organization should process. One more thought process of DeepLab is to assign multi-scale relevant element gaining through the accumulation of elements acquired from pictures at particular scales. DeepLab uses an ImageNet pre-prepared leftover brain organization (ResNet) for extricating highlights in the pictures [76-77]. Besides, rather than traditional convolutions, they utilize (widened) convolutions where the modifying expansion paces of every convolution license the ResNet square to get multi-scale context-oriented information [78-101].

U type neural networks are deep encoders and decoders-based architecture, also termed semantic pixel-wise segmentation [102-134]. Corresponding to the decoder's orientation invariance capabilities, it encodes the input image into low dimensions that are later recovered along with it. This renders a segmented image at the decoder end [8].

## 3. CNN-U-NET Layer

Pixel-wise semantic segmentation necessitates the labeling of individual pixels. In this semantic segmentation method, tumor labeling is grounded on the classes andsegregates all the pixels into individual categories [135-145]. Figure 1 illustrates the CNN-U-NET layer architecture. The CNN-U-NET system comprises three layers such as input layer, convolutional layers, and full connection layer. Moreover, contracting path or downsampling path, bottleneck path, and expanding path or upsampling path are three U-NET architecture paths. Every up and downsampling path consists of 4 blocks, and the downsampling block is built with a 3∗3 convolution layer with an activation function and a 2∗2 max-pooling layer. The number of feature maps has doubled in every pooling operation in the U-NET layers. The input MRI is a 240∗240-pixel image, starting with 32 feature maps for the first block in the pooling operation, 64 for the second, and sequentially repeated. This contracting path pooling operation intends to obtain the input image context information for segmentation [146-171]. The skip connections are utilized to retrieve coarse contextual details and transfer them to the upsampling path [172-185]. The network connectedness between the contracting and expanding paths is constituted in U-NET architecture with the bottleneck path [186-196]. Two convolutional layers build the bottleneck for connecting with the expanding path.

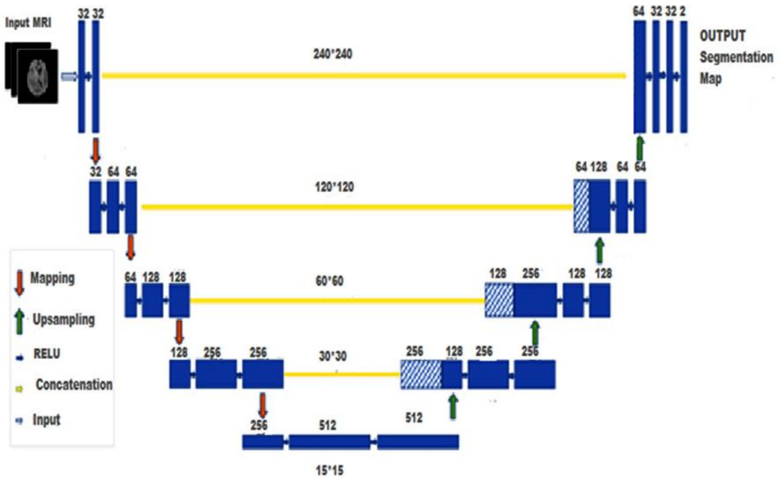


**Figure 1.** CNN-U-NET Layer Architecture

## 4. CNN U-NET Single Scale with Multi-Modality

Initially, single modal images were used as a single input to train the independent segmentation networks. These single modal images can give more information and intriguing details because the quantity of data is precise and processed less. They are advantageous in detailing individual features represented in the network layers, providing better predictions.With T1 and T2 checks, the mind would seem lighter in the center and have hazier shades encompassing it. The inverse would happen with FLAIR checks with the dull regions toward the center and lighter shades encompassing. A T1c check shows tissues with a high-fat substance (like white matter) show up brilliant, and compartments loaded up with water (CSF) seem dim. This is great for exhibiting life structures. A T2-weighted examine compartment loaded with water (like CSF compartments) shows up splendid, and tissues with a high-fat substance (like white matter) seem dull. This is great for exhibiting pathology since the overwhelming majority of sores (harmed tissue) will generally foster edema and are related to an increment in water content, with extra RF heartbeat and extra control of the attractive slopes.

The T2-weighted grouping can be changed over to a FLAIR succession, wherein free water is dim; however, edematous tissues stay brilliant. Specifically, this arrangement is the touchiest method for assessing the cerebrum for demyelinating illnesses, like MS. Upgraded T1 and T2-weighted MRIs, can portray intense dynamic MS injuries. These show up as upgrading white matter injuries, and the presence of an improving sore has been displayed to expand the explicitness for MS. Best growth picture model is T1c imaging can likewise be performed while imbuing Gadolinium (Gad). Stray improved pictures are particularly valuable in taking a gander at vascular constructions and breakdown in the blood-mind hindrance, e.g., growths, abscesses, aggravation (herpes simplex encephalitis, numerous sclerosis). So, the T1c imaging is the best outcome in delivering thesingle model's growth picture model.

## 5. Multi Modal CNN U-NET

We demonstrate the ability of the algorithm for image segmentation through Multi-modality with different scales such as CNN scale1 (12∗12) (Single model T1c), CNN scale2 (24∗24) (Single model T1c), and CNN scale3 (48∗48) (Single model T1c). Table 1 depicts that the increasing scale size would gradually increase the segmentation results.

**Table 1:** Multimodal with small scales

| Scale size | Dice Coefficient | Positive Predictive Value | Sensitivity | Accuracy |
|---|---|---|---|---|
| UNET CNN-Scale1 (12∗12) | 0.75 | 0.735 | 0.739 | 0.783 |
| UNET CNN-Scale2 (24∗24) | 0.756 | 0.749 | 0.747 | 0.792 |
| UNET CNN-Scale3 (48∗48) | 0.761 | 0.753 | 0.755 | 0.803 |

Henceforth, the following scale values were increased to verify the impact on segmentation results regarding the smaller scales. The CNN scale1, 2, 3 (64∗64, 128∗128, 240∗240) were used as inputs in the model, and the outcomes showed a similar trend as in the previous scales. These scaleswere also used for Multi-modality in the previous scales. Outcomes followed the previously studied scales where the increasing scales showed improved image segmentation reflected in the dice coefficient and accuracy.

**Table 2:** Multi model with larger scales

| Scale size | Dice Coefficient | Positive Predictive Value | Sensitivity | Accuracy |
|---|---|---|---|---|
| UNET CNN-Scale1 (64∗64) | 0.79 | 0.771 | 0.801 | 0.875 |
| UNET CNN-Scale2 (128∗128) | 0.805 | 0.792 | 0.806 | 0.887 |
| UNET CNN-Scale2 (240∗240) | 0.8306 | 0.8203 | 0.8492 | 0.898 |

The proposed strategy, contrasted and the 12∗12, 24∗24, and 48∗48 scales to the best three scales, created higher exactness values than 240∗240, 128∗128, and 68∗68 scales. Obviously, by joining both worldwide and neighborhood highlights by 240∗240, 128∗128, and 68∗68 scales, the exactness is improved and comes to almost 0.898 for the dataset (table 2).

## 6. Conclusion

This proposed model accomplishes great outcomes on account of the remarkable U-NET construction. The proposed strategy accomplishes preferred execution with precision over the other

CNN scale models from these outcomes. The aftereffect of this analysis was great because the elements learned by the U-NET are registered in the neighborhood and worldwide areas. In this proposed approach, 100 ages acquired better results over different scales. This is accomplished because of the consolidated 64∗64, 128∗128, and 240∗240 scales that contain more data than individual scales. For every age, the division result is refined and redressed.

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